Equilibrium Storage in a Markov Economy

Anna Creti*  
Università Bocconi  
Bertrand Villeneuve†  
University of Tours  
Finance of Energy Markets Laboratory‡  
September 2007

Abstract

We model an economy that alternates randomly between abundance and scarcity episodes. We develop an original method to characterize in detail the structure of the Markovian competitive equilibrium. Accumulation and drainage of stocks are the main focuses. Economically appealing comparative statics results are proved. We also characterize stationary distribution of states. We extend the model to discuss price stabilization policies, injection and release costs, and limited storage capacity. Overall, the analysis delineates the notion of “flexible economy.”

Keywords. Price stabilization, strategic stocks, supply risk

JEL codes. C61, Q48, L90.

*Anna Creti, Università Bocconi and IEFE, Via Sarfatti 25, 20136 Milan, Italy. Email: anna.creti@unibocconi.it.
†Corresponding author. Bertrand Villeneuve, CREST-J320, 15 boulevard Gabriel Péri, 92245 Malakoff cedex, France. Email: bertrand.villeneuve@ensae.fr.
‡Joint Laboratory Paris Dauphine University, CREST and EDF R&D.
§This research has benefited of the support of the Chair Dauphine-EDF-Calyon “Finance and Sustainable Development: Quantitative Approaches”.
1 Introduction

Storage models are hard to tackle. Even the simplest specification of the production and storage technologies leads to intractable equations. Most results involve proving existence and uniqueness of the equilibrium, together with some qualitative properties (prices are monotonic in stock and in storage cost, stockouts happen with positive probability and stocks have an upper limit). As far as simulation based econometrics (GMM estimators as in Deaton and Laroque, 1992, 1996) or the illustration of a theoretical possibility are concerned (convenience yield, analysis of the Samuelson effect, backwardation as in Routledge et al, 2000), this is a suitable approach. Our aim is not to extend the existing models but rather to propose a simple case set in continuous time to facilitate the parameterization of shock persistence, and to characterize finely the behavior of the economy.

Our approach is innovative as it does not rely on fixed point methods, but directly constructs the equilibrium, assuming that agents observe the random occurrence of the so-called abundance and scarcity periods. We focus on a Markov economy, so the competitive equilibrium consists of price functions that only depend on the current state. We fully describe the dynamics of accumulation and drainage by means of a system of differential equations. Relying on the phase diagram, we identify a number of economic border conditions and prove existence and uniqueness of the equilibrium. Technically, we confront a Boundary Value Problem with conditions imposed on singular points.

In such an equilibrium, stocks are smoothly piled up in an abundance state and smoothly drained in a crisis state. The relationship between the state of the economy (the endogenous stocks and the exogenous random variable) and the price is informative about behavior of the economy. For example, we can see that the upper bound of the stocks is never reached in finite time and we can also evaluate the speed at which stocks are drained out. Besides such qualitative results, we provide comparative statics on the upper bound of the stocks and equilibrium price schedules with respect to all the parameters of the model.

1 The notion of convenience yield was introduced by the economists Kaldor and Working who studied the theory of storage. In the context of commodities, the convenience yield captures the benefit from owning a commodity minus the cost of storing it. The flow of benefits from storage (the reduction in production costs) drives a wedge between the price of a commodity today and its value in the future.

2 The Samuelson effect arises when, for a given commodity, forward price volatility declines with the contract horizon.

3 Backwardation occurs when the price of a commodity for the actual period exceeds the price for future periods.
Price functions give a logically complete picture of the equilibrium. Nevertheless, the characterization of the stationary distribution of states has an intuitive appeal as it directly informs as to where the economy is likely to be. The frequency of stockouts as well as the propensity of the economy to adjust stocks can thus be assessed. The stationary distribution is described by differential equations, which opens up the way to qualitative analysis and comparative statics. The dependency of the shape of the state density to the parameters is addressed.

Our model is motivated by two economic issues placed high on the European policy agenda. Storage as determined in response to persistent shocks is instructive for the energy policy debate about the role of gas or petroleum strategic reserves to manage supply disruptions, especially when dependency on foreign resources raises serious concerns. The existing theoretical literature on energy supply security, mostly inspired by the theory of exhaustible resources, considers either the extraction rate of one country when foreign import, though needed to complement national production, can suddenly default, or strategic behavior of consuming countries confronting oligopolistic or cartelized supply. However useful these analyses may be for the long run, they ignore the question of how to reach any desired stock level and how to deal with uncertainty about the duration of supply disruption. Efficiency loss of recommended policies may be underestimated.

We also shed some light on the banking of CO\textsubscript{2} pollution permits, a financial mechanism whose application is being discussed in the context of the European Trading Scheme, i.e. a market-based approach to environmental control. A number of research works have already analyzed the role of uncertainty in emission permit markets, studying in particular the SO\textsubscript{2} banking mechanism allowed by the American Clean Air Act. Most results concern optimum individual strategy and not the equilibrium. This limitation notwithstanding, several aspects of risk-averse utilities' are studied.

\textsuperscript{4} This trade-off has been analyzed by several authors (for example Stiglitz, 1977, Sweeney, 1977, Hillman and Van Long, 1983, Hugues Hallet, 1984).


\textsuperscript{6} On the role of banking in smoothing permit prices, see Carlson and Sholtz (1994) and Godby et al (1997), on its effect on control costs, see Montero (1997). Hennessy and Roosen (1999), Ben-David et al (2000) and Baldursson and von der Fehr (2004) examine the impact of stochastic pollution on production decisions in competitive markets, showing that the existence of uncertainty as to the magnitude of pollution tends to reduce production activities to the situation of non-stochastic pollution with the same mean rate of emissions. Rousse and Sévi (2006) use a methodology similar to the one proposed by the models on precautionary saving with uncertainty on future income. Econometric estimates on US data provide evidence that utilities bank in response to uncertainty, particularly...
The study of equilibrium in Schennach (2000) assumes that risk-neutral firms minimize their expected discounted costs. When firms anticipate the possibility of a permit stockout, the expected change in marginal abatement costs could be negative. Potential permit stockout could partially explain normal backwardation in permit prices; the same mechanism is at the core of the results in Routledge et al (2000). Our analysis is not focused on financial phenomena, though the model could serve that purpose; this said, we can illustrate the precautionary motive for banking emission rights, when the output market alternates between booms and busts (namely, when electricity demand is influenced by unexpected climate constraints) or there is a sudden but temporary increase in input costs.

The economic relevance of our model and its practicality are illustrated by three extensions.

First, we study the impact of a constant price policy. This apparently extreme choice is instructive for both gas and pollution permit markets because a regulatory authority could be tempted to stabilize gas or permit prices around a particular target (or path) of prices. Understanding the mechanisms of equilibrium and comparison with more interventionist policy could serve as a modest guide (or a development thereof) for market design and regulation. In contrast to the previous abundant literature on storage and price stabilization, results are clear-cut: perfect price stabilization can be reached only if the economy is prepared to let stocks go to infinity. This simple prediction gives a partial answer to doubts as to price stabilization models raised by Williams and Wright (1991), who affirm: “[...] the possible permutations of demand curvature, disturbance structure, initial conditions, supply elasticity and so forth seem nearly infinite. [...] That is the main point: few, if any, general propositions are possible.”

In a second extension of the model, we consider the impact of nonnegligible injection and release costs. This better characterizes natural gas or oil storage. Starting from the observation that the commodity is different when their power is mainly coal-generated.

---

7 Massel (1969), generalizing previous results by Waugh (1944) and Oi (1961), considers stabilization at exactly the mean price as a decision made to eliminate price fluctuations, presumably enhancing welfare. A costless stock established by an authority achieves the objective and enhances welfare. Welfare analysis of price stabilization has been extended to encompass alternative assumptions about price expectations, risk attitudes (Newbery and Stiglitz, 1981), and nonlinearities (Turnovsky, 1974, 1976, among others). Storage in this literature is made by a public authority, which is in charge of managing a buffer stock. Helmerber and Weaver (1977) is the only model that questions the optimality of stabilization schemes. The private storage industry and arbitrage opportunities are considered, instead, in modern dynamic stochastic models with i.i.d disturbances (Williams and Wright, 1991).
depending on whether it lies outside or inside the reservoir, we show that the results of our analysis are unaffected by this generalization.

Limited storage capacity is also a crucial issue. For instance, gas is often stored in specific natural facilities (such as salt caverns) that are scarce. Also, market rules for emission programmes could impose the use of banking CO2 permits up to a given threshold only. Consistently with the idea of scarcity rent, we show that in the accumulation phase, the price for storage service suddenly jumps above marginal cost when the capacity saturates. Interestingly, we find that, in contrast with the unconstrained case, the maximal stock is attained in finite time if the state of abundance is sustained.

The paper is organized as follows. Section 2 sets up the model and section 3 describes the methodology we follow to solve it. Section 4 characterizes the solution qualitatively and quantitatively and proposes comparative statics. Section 5 exposes the statistical properties of the model. Section 6 is devoted to applications and extensions of the model, while Section 7 concludes on the notion of economic flexibility. Proofs are relegated to the Appendix.

2 The model

2.1 Assumptions and parameters

The economy can be in two states, abundance (A) or scarcity (C, for crisis). A generic state is denoted $\sigma$. Time is continuous and the state changes following conditional Bernoulli processes: the passage from A to C occurs with probability rate $\lambda_C$, and the passage from C to A with probability rate $\lambda_A$. This simple Markov structure captures the fact that regimes have uncertain nature and duration that can be quantified statistically. The unconditional probabilities of states A and C are, respectively, $\Pr[A] = \frac{\lambda_A}{\lambda_C + \lambda_A}$ and $\Pr[C] = \frac{\lambda_C}{\lambda_C + \lambda_A}$. The ratio $\lambda_A/\lambda_C$ represent the relative frequencies of the two states whereas $2(\lambda_A^{-1} + \lambda_C^{-1})^{-1}$ measures the global rate of change.8

Primary production and final demand at a given date are assumed to be nonstrategic (price-taking behavior), they vary with the state and the current price. Consequently, the fundamental data are, for every $\sigma = A, C$ and every price $p$, the excess supply functions, i.e. the difference, denoted

8The unconditional rate of change is twice the harmonic mean of the conditional rates of change

$$\Pr[A] \times \lambda_C + \Pr[C] \times \lambda_A = \frac{2}{1/\lambda_A + 1/\lambda_C}. \tag{1}$$
\[ \Delta_{\sigma}[p], \] between production and final consumption.\(^9\) These functions measure variations per unit of time, thus conservation of matter imposes that \( \Delta_{\sigma}[p].dt \) be the variation of the stocks in a time interval of length \( dt \) during which state \( \sigma \) would be sustained.\(^10\) These two functions are assumed to be strictly increasing and to have unique, finite, zeros in \( \mathbb{R}_+ \) denoted by \( p^*_\sigma \). These zeros are the prices at which primary production and final consumption would be balanced at each instant, were state \( \sigma \) sustained. To clarify matters, \( p^*_C > p^*_A \).

Storage is assumed to be competitive and to exhibit constant returns to scale, with carrying costs being the (constant) opportunity cost of capital \( r \) and a unit flow cost \( c \) (paid per unit of commodity and per unit of time).\(^11\) Storers are assumed to be risk-neutral so prices satisfy the following relationship

\[ p_t + cdt = (1 - rdt)E_t p_{t+dt}. \] (2)

The LHS is acquisition price plus stockholding cost over interval \( dt \) and the RHS is the expected present value (as for date \( t \)) of the stock at date \( t + dt \).

**Definition 1** A competitive equilibrium is an initial state (\( C \) or \( A \) and a certain stock) at date 0 (without loss of generality), plus a sequence of prices \( \{p_C[S,t], p_A[S,t]\}_{t \geq 0} \) such that (1) all agents (consumers, producers, storers) are price-takers and form rational expectations; (2) in each state, conservation of matter imposes that current production minus current final consumption equals the variation in the stocks.

**Definition 2** A Markovian competitive equilibrium is such that the equilibrium sequence of prices only depends on the current state \( (\sigma, S) \), but neither the date nor the past.

The following focuses on Markovian equilibria, summarized by functions \( p_C[S] \) and \( p_A[S] \) (time as an argument can be dropped).

### 2.2 Fundamental equations

The price functions are necessarily continuous in \( S \) over the support of the equilibrium, otherwise the predictable discontinuity would create an arbitrage.

---

\(^9\)These assumptions as similar to those in Deaton and Laroque (1992, 1996) and Routledge \textit{et al} (2000). They are consistent with general equilibrium if, for example, infinite horizon consumers have quasi-linear utility (this supposes two goods per period, the storable commodity plus a numéraire that could be leisure); the rate of interest is then directly given by the discount rate.

\(^10\)Shocks can be interpreted as demand or supply shocks. Only the net shock matters.

\(^11\)The assumption in Deaton and Laroque (1992, 1996) and Routledge \textit{et al} (2000) is that a constant fraction of the stock vanishes every period. This type of cost can be included, via a renaming of variables, in \( r \). Our variation is well suited to natural resources.
trage opportunity (e.g. massive buys/sales just before discrete upward/downward jump).

For all $S > 0$ and a time increment $dt$, the no-arbitrage equations derived from (2) read

$$p_C[S] + cdt = (1 - rdt) \left((1 - \lambda_A dt) \cdot p_C[S + dS] + \lambda_A dt \cdot p_A[S + dS]\right), \quad (3)$$

$$p_A[S] + cdt = (1 - rdt) \left((1 - \lambda_C dt) \cdot p_A[S + dS] + \lambda_C dt \cdot p_C[S + dS]\right). \quad (4)$$

This is a first-order approximation. We let $dt$ converge to 0 and neglect second-order terms, thus (3) and (4) become

$$\Delta C[p_C] \cdot \frac{dp_C}{dS} = (r + \lambda_A)p_C - \lambda_A p_A + c, \quad (5)$$

$$\Delta A[p_A] \cdot \frac{dp_A}{dS} = (r + \lambda_C)p_A - \lambda_C p_C + c. \quad (6)$$

The boundary value problem basically states that the solution must verify equations (5), (6), $p_C[0] = p_C^*$ and $p_A[S^*] = p_A^*$, where $S^*$ is the maximum stock. One difficulty is that $\Delta_C[p_C[0]] = 0$, meaning that $\frac{dp_C[0]}{dS}$ is infinite. Another difficulty is that $S^*$ is only implicitly defined, its value being determined as the point where accumulation stops ($p_A[S^*] = p_A^*$ implies that $\Delta_A[p_A[S^*]] = 0$); moreover, at $S^*$, the RHS of (6) and both factors in the LHS are null, meaning that one condition is imposed at a singular point.

### 2.3 Summary of the notation

- $t$: time;
- $\sigma$: generic exogenous state; $C$: Scarcity/Crisis; $A$: Abundance;
- $\lambda_C$: probability rate that state passes from $A$ to $C$;
- $\lambda_A$: probability rate that state passes from $C$ to $A$;
- $\Delta_\sigma[p]$: excess supply for price $p$ in state $\sigma$ (per unit of time);
- $p_\sigma^*$: zero of $\Delta_\sigma$;
- $S$: stocks at a given date;
- $c$: marginal storage cost (per unit of time);
- $r$: riskfree interest rate.

### 3 The equilibrium

This section establishes that in a Markovian equilibrium, stocks are smoothly piled up in state $A$ and smoothly drained in state $C$. Moreover, stocks vary between 0 and the upper bound $S^*$ to be determined, whereas the price is bounded below by $p_A^*$ and above by $p_C^*$. 7
We analyze the system of equations in a phase diagram \((p_C, p_A)\) in which \(S\) is the underlying parameter. This representation facilitates the demonstration of existence and uniqueness of the equilibrium. Most importantly for economic intuition, it enables qualitative results and comparative statics.

### 3.1 Phase diagram

Let us define \(x_\sigma\), a function of \(S\), by differential equation \(x'_\sigma = \Delta_\sigma[p_\sigma] \cdot p'_\sigma\), with \(x_C[0] = 0\) and \(x_A[S^*] = 0\). Using this notation in equations (5) and (6), we obtain

\[
\begin{align*}
x'_C &= (r + \lambda_A)p_C - \lambda_A p_A + c, \quad (7) \\
x'_A &= -\lambda_C p_C + (r + \lambda_C)p_A + c. \quad (8)
\end{align*}
\]

We have an autonomous \((S\) is not in the equations\) system of separated variables. We draw the two-dimensional phase diagram with \(p_C \leq p_C^*\) on the horizontal axis and \(p_A \geq p_A^*\) on the vertical one. This quadrant is partitioned into three regions, separated by the isoclines where \(x'_C = 0\) and \(x'_A = 0\) are null, i.e.

\[
\begin{align*}
(r + \lambda_A)p_C - \lambda_A p_A + c &= 0 \quad \text{and} \quad p_C \leq p_C^*, \quad p_A \geq p_A^*. \quad (CC') \\
-\lambda_C p_C + (r + \lambda_C)p_A + c &= 0 \quad \text{and} \quad p_C \leq p_C^*, \quad p_A \geq p_A^*. \quad (AA')
\end{align*}
\]

\((CC')\) is never empty since by assumption \(p_C^* > p_A^*\). \((CC')\) is above \((AA')\) in the considered quadrant (see Appendix A.1).

The phase diagram in Figure 1 indicates the shape and relative positions of the trajectories satisfying the motion equations (7) and (8). We define the lowest region, \(I\), as the triangle having \((AA')\) as a side and \((p_C^*, p_A^*)\) as a vertex; the intermediate region, \(II\), lies between the two lines, and the highest region \(III\) is above \((CC')\). In \(I\), \(p_C' < 0\) and \(p_A' < 0\); in \(II\), \(p_C' > 0\) and \(p_A' > 0\); in \(III\), \(p_C' > 0\) and \(p_A' > 0\).\(^{12}\)

The intersection between \((AA')\) and horizontal straight line \(p_A = p_A^*\) is especially remarkable. We denote it as \(\Omega = (\frac{r+\lambda_C}{\lambda_C}p_A^* + \frac{c}{\lambda_C}, p_A^*)\).

### 3.2 Characterization

**Proposition 1**

1. In equilibrium, the support of \(S\) is an interval \([0, S^*]\).

\(^{12}\)This comes from the facts that in \(I\), \(x'_C > 0\) and \(x'_A < 0\); in \(II\), \(x'_C > 0\) and \(x'_A > 0\); in \(III\), \(x'_C < 0\) and \(x'_A > 0\).
2. Stocks are drained during scarcity episodes and accumulated during abundance episodes ($\Delta_C[p_C[S]] \leq 0$ and $\Delta_A[p_A[S]] \geq 0$ over $[0, S^*]$).

3. The equilibrium trajectory $\{(p_C[S], p_A[S])|S \in [0, S^*]\}$ is in region I. The trajectory starts with $p_C[0] = p_C^*$ and stops at $(p_C[S^*], p_A[S^*]) = \Omega$.

4. There is storage in equilibrium (i.e. $S^* > 0$) if and only if

$$(r + \lambda_C)p_A^* + c < \lambda_Cp_C^*.$$ 

5. The equilibrium is unique

The overall behavior of the prices in equilibrium can be summarized as follows: the unique equilibrium trajectory is necessarily in I, $S$ varies in the interval $[0, S^*)$ and $p_A[S] > p_A^*$ and $p_C[S] < p_C^*$ for $S > 0$ and $S < S^*$, and $p_A[S]$ and $p_C[S]$ decrease with respect to the level of the stock.

Figure 1 shows the shape of the equilibrium trajectory. The condition for positive storage $(r + \lambda_C)p_A^* + c < \lambda_Cp_C^*$ has a precise economic meaning: crises have to be sufficiently likely and/or sufficiently marked to justify storage. If this condition were not satisfied, there would be no stocks in equilibrium: the price would alternate back and forth between $p_A^*$ in state $A$ and $p_C^*$ in
state \( C \). To avoid this uninteresting case, we assume that the condition for positive storage is satisfied.

### 3.3 Computations

Numerically, the argument used in the proof of Proposition 1 (point 5) has an extremely useful implication: any starting point close to \( \Omega \) is on a trajectory that is closer to the equilibrium as we go to the right (i.e. as \( S \) decreases) in the phase diagram. In other terms, we can control the maximum error on prices at the starting point (close to \( \Omega \)) given that the system of equations is self-correcting as \( S \) decreases.

Moreover, the system of equations (7, 8) is autonomous, so leaving aside boundary conditions, we know that if \((p_C[S], p_A[S])\) follows the equilibrium trajectory for \( S \in [\underline{S}, \overline{S}] \), so does \((p_C[S + \theta], x_A[p + \theta])\) for \( S \in [\underline{S} - \theta, \overline{S} - \theta] \) where \( \theta \) is an arbitrary real.

We can now suggest the following algorithm.

**Algorithm 1 (Trajectory)**

1. Fix arbitrarily the upper bound at some arbitrary value \( \overline{S} \).
2. Choose \( \varepsilon > 0 \) as small as needed. Consider the trajectory through \((p_C[\underline{S}] = \frac{r + \lambda C}{\lambda C} p_A^* + \frac{c}{\lambda C}, p_A[\underline{S}] = p_A^* + \varepsilon)\), a point above \( \Omega \).
3. Solve the differential equations numerically and find the stock \( \underline{S} < \overline{S} \) such that \( p_C[\underline{S}] = p_C^* \).
4. Shift the calculated functions \( p_C \) and \( p_A \) to the left by an amount \( \underline{S} \); \( \underline{S}^* = \overline{S} - \underline{S} \) approximates the upper bound \( S^* \).

The error is controlled by \( \varepsilon \) (a uniform bound on the error). Remark that along a trajectory,

\[
\frac{dS}{dp_C} = \frac{\Delta_C[p_C]}{(r + \lambda_A)p_C - \lambda_A p_A + c}
\]  

(9)

is well defined over the range of \( p_C \) i.e. \([\frac{r + \lambda C}{\lambda C} p_A^* + \frac{c}{\lambda C}, p_C^*]\) (trajectory is bounded away from \((CC')\)). Thus we can calculate \( S^* \) as accurately as desired by computing:

\[
S^*_\varepsilon = \int^{p_C}_{\frac{r + \lambda C}{\lambda C} p_A^* + \frac{c}{\lambda C}} \frac{\Delta_C[p_C]}{(r + \lambda_A)p_C - \lambda_A p_A + c} dp_C.
\]  

(10)
4 Behavior of the economy

4.1 Comparative statics

In the absence of an explicit expression of price functions and $S^*$, the comparative statics relies on exploitation of the phase diagram.

**Proposition 2 (Comparative statics)** For all $S$ in the support, and for all states $\sigma = C, A$

\[
\frac{\partial p^*_\sigma[S]}{\partial c} < 0; \quad \frac{\partial p^*_\sigma[S]}{\partial r} < 0; \quad \frac{\partial p^*_\sigma[S]}{\partial \lambda_A} < 0; \quad \frac{\partial p^*_\sigma[S]}{\partial \lambda_C} > 0.
\]

(11)

and consequently

\[
\frac{\partial S^*}{\partial c} < 0; \quad \frac{\partial S^*}{\partial r} < 0; \quad \frac{\partial S^*}{\partial \lambda_A} < 0; \quad \frac{\partial S^*}{\partial \lambda_C} > 0.
\]

(12)

The interpretations are straightforward. An increase in the unit storage costs discourages accumulation, thus at any level of the stocks, the value of the commodity is smaller. Storers will tend to pile up stocks more slowly in abundance, and to run them down faster during crisis. Also, rarer crises diminish the expected yield from storing, to the same effect. This logic has direct consequences on the comparative statics of the limit stock: the value $S^*$, defined as the solution to equation $p^*_\sigma[S] = p^*_\lambda$, must decrease if function $p^*_\lambda[S]$ is diminished.

**Linear case.** The effects of varying excess supply functions are intricate if we do not restrict the analysis to a specific parametric family. For example, in the noteworthy case of linear excess supply functions, precise results can be found.

**Proposition 3 (Linear case)** Assume that

\[
\Delta^\sigma[p_\sigma] = \beta_\sigma(p_\sigma - p^*_\sigma) \text{ with } \beta_\sigma > 0 \text{ and } p^*_\sigma > 0.
\]

(13)

1. For all $S$ in the support and all states $\sigma = C, A$

\[
\frac{\partial p^*_\sigma[S]}{\partial p^*_C} > 0; \quad \frac{\partial p^*_\sigma[S]}{\partial p^*_A} > 0; \quad \frac{\partial p^*_\sigma[S]}{\partial \beta_C} > 0; \quad \frac{\partial p^*_\sigma[S]}{\partial \beta_A} < 0.
\]

(14)

and consequently

\[
\frac{\partial S^*}{\partial p^*_C} > 0; \quad \frac{\partial S^*}{\partial \beta_C} > 0; \quad \frac{\partial S^*}{\partial \beta_A} < 0.
\]

(15)

The sign of $\frac{\partial S^*}{\partial p^*_A}$ is ambiguous.
2. As a function of $\beta_C$ and $\beta_A$, $p^*_C[S]$ and consequently $S^*$ are homogeneous of degree 1.

It is plain that a bigger $p^*_C$ should increase the value of storage, hence the effect on prices and maximum stocks. In contrast, a bigger $p^*_A$ has two effects: on the one hand, it increases the price at which stocks are built and thus prices in crisis have to increase altogether to motivate positive holding; on the other hand, the range of prices tightens, meaning that potential gains from the occurrence of a crisis could vanish at smaller values of $S$. This explains the ambiguity of the impact of $p^*_A$ on $S^*$.

A higher parameter $\beta_C$ means that a given release has a less depressing effect on the price. In other terms, the profitability of storing in view of releasing at high price when state $C$ arises is better warranted. This gives incentives to store more. A higher parameter $\beta_A$ implies that building stocks is easier, since piling up has a lesser inflationary effect on the price, hence the negative effect on the equilibrium price. The second point of the proposition illustrates that the first effect dominates when $\beta_C$ and $\beta_A$ are increased in the same proportion.

4.2 Approximate price functions

To better describe the behavior of the economy, we clarify the properties of the equilibrium when stocks are almost empty or close to their maximum. We see in particular how stocks are drained down and why the maximum stocks are not attained in finite time.

**Draining out the stock.** At $S = 0$, $x'_C$ is finite and different from 0 (see equation 7); more precisely, $x_C[S] \sim K_C S$ with $K_C = (r + \lambda_A)p^*_C + c - \lambda_A p_A[0] > 0$. This implies (see Appendix A.5) that

$$p_C[S] - p^*_C \sim -\sqrt{\frac{2K_C}{\Delta_C[p^*_C]}} S^{1/2}$$

Equation (16)

$p_C$ is vertically tangent at 0 (Figure 2). As a consequence, if the economy stays in crisis, the complete drainage of the stocks happens in finite time. To show this, it suffices to integrate in a neighborhood of 0 the differential equation

$$\frac{dS}{dt} = \Delta_C[p_C[S[t]]],$$

Equation (17)

where the RHS can be replaced by its approximation. As long as the economy stays in crisis, starting—without loss of generality—with $S_0$ at date 0, the
integration of equation (17) yields

\[ S(t) \simeq \left( \sqrt{S_0 - \frac{\Delta_C[p^*_C]K_C}{2} t} \right)^2. \]  

(18)

Drainage exhibits smooth landing: the limit of the rate of withdrawal is zero; but drainage time is finite. It is approximately

\[ T_0 \simeq \sqrt{\frac{2S_0}{\Delta_C[p^*_C]K_C}}. \]  

(19)

This implies that the economy is protected only twice as long when stocks are quadrupled.

The comparative statics on \( K_C \) is based on (11) in Proposition 2. We have \( \frac{\partial K_C}{\partial \lambda} < 0 \), meaning quite naturally, that a larger propensity to return to the scarcity state slows down drainage (precaution). Also, \( \frac{\partial K_C}{\partial c} > 0 \) and \( \frac{\partial K_C}{\partial r} > 0 \), meaning that higher storage costs accelerate drainage for given stocks. Remark that \( \frac{\partial K_C}{\partial A} = (p^*_C - p_A[0]) - \lambda_A \frac{\partial p^*_C[0]}{\partial A} > 0 \) : a higher propensity to return to abundance also accelerates drainage (preservation value is diminished).

**Replenishing.** The upper bound \( S^* \) corresponds, as we noticed in subsection 3.2, to a singular point. The calculation of an approximate solution requires several steps. We show in the Appendix A.5 that \( x_A[S] - x_A[S^*] \sim S^* K_A^2 (S - S^*)^2 \), where \( K_A \) is a non-negative real number. This implies that \( p_A \) has a negative finite non-null derivative at \( S^* \) (Figure 2):

\[ p_A[S] - p_A^* \sim S^* K_A (S - S^*). \]  

(20)

Even if the economy stays in a state of abundance, the upper bound \( S^* \) is never reached in finite time. The reasoning reminds us of Zeno’s classical paradox, Achilles and the Tortoise. As \( p_A \) covers half its difference with the limit \( p_A^* \), the variation rate of the stock per unit of time, namely \( \Delta_A \), is approximately halved (linear approximation of excess demand at \( p_A^* \)), meaning that the convergence speed \( dS/dt \) is approximately halved. This implies that, whatever the proximity of the target, the duration to cover half the distance to the target is approximately constant, thus the target is never attained.

**Example.** Using the algorithm of subsection 3.3, we solve numerically the system with the parameters in Table 1. The time unit could be the year. We find approximately \( S^* \simeq 9.5 \). See Figure 2.
Figure 2: Price functions.

Table 1: Parameter values

<table>
<thead>
<tr>
<th>Category</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Financial and physical costs</td>
<td>( r = .1 )  ( c = .1 )</td>
</tr>
<tr>
<td>Linear excess supply</td>
<td>( \beta_C = 1 )  ( p_C^* = 5 )  ( \beta_A = 5 )  ( p_A^* = 1 )</td>
</tr>
<tr>
<td>Rates of jumps</td>
<td>( \lambda_C = 1 )  ( \lambda_A = 1 )</td>
</tr>
</tbody>
</table>

5 Stock statistics

A state is described by the stock \( S \) and the conjuncture (\( C \) or \( A \)). All states \( S \in [0, S^*] \) with \( S' < S^* \) are crossed in finite time with probability 1: starting from an arbitrary state, it is easy to find a history (or a set of histories) that leads to another arbitrary state in finite time, this history being associated with positive probability (it suffices to have a long enough accumulation followed by a long enough drainage, or the other way around). Since the equilibrium is Markovian, this property guarantees that there is a unique stationary distribution. This section is essentially devoted to the analysis of this stationary distribution.
5.1 Dynamics

The statistical evolution of the system over time when we observe perfectly
the state at a given date is covered in Appendix A.6.

A feature of the model is that in the long run initial information loses
relevance. Interior states (i.e. values of \( S \) different from 0 and \( S^* \)) are just
crossed as accumulation or drainage goes on; boundary states, if reached,
remain in force until a downward or upward jump occurs. Thus, in the long
run, \( S = 0 \) and \( S = S^* \) are associated with probabilities whereas values in
between are associated with densities.

**Densities.** Assume that, for interior values of the stock \( S \in (0, S^*) \), a
density \( f_\sigma[S, t] \) (with \( \sigma = C, A \)) represents the information we have on the
system. Take \( \sigma = C \) to fix ideas. Choose \( S_1 \) and \( S_2 \) (0 < \( S_1 < S_2 < S^* \)) two
levels of the stocks. By definition

\[
\Pr[C, S \in [S_1, S_2], t] = \int_{S_1}^{S_2} f_C[S, t]dS. \tag{21}
\]

This gives

\[
\frac{d\Pr[C, S \in [S_1, S_2], t]}{dt} = f_C[S_1, t] \cdot \Delta_C[p_C[S_1]] - f_C[S_2, t] \cdot \Delta_C[p_C[S_2]]
+ \lambda_C \int_{S_1}^{S_2} f_A[S, t]dS - \lambda_A \int_{S_1}^{S_2} f_C[S, t]dS, \tag{22}
\]

where the first two terms represent the endogenous evolution of the stocks if
the economy remains in crisis, and the third and fourth terms represent the
exogenous jumps in and out of the segment due to state changes. Figure 3
illustrates this probability balance.

To find the dynamics of the density, we make \( S_2 \) converge toward \( S_1 \) to get

\[
\frac{df_C[S, t]}{dt} = -\frac{d}{dS} (f_C[S, t] \cdot \Delta_C[p_C[S]]) + \lambda_C f_A[S, t] - \lambda_A f_C[S, t]. \tag{23}
\]

Similarly

\[
\frac{df_A[S, t]}{dt} = -\frac{d}{dS} (f_A[S, t] \cdot \Delta_A[p_A[S]]) + \lambda_A f_C[S, t] - \lambda_C f_A[S, t]. \tag{24}
\]
Figure 3: Probability balance between $t$ and $t + dt$.

**Probabilities.** States $S = 0$ or $S^*$ are associated with probabilities. We have\(^{13}\)

$$\frac{d\Pr[C,0,t]}{dt} = -\lambda_A \Pr[C,0] - \lim_{S \to 0} (f_C[S,t] \cdot \Delta_C[p_C[S]]) ,$$

(25)

where the first-term represents jumps out (jumps in are negligible since $\Pr[A,0,t] = 0$; due to accumulation, this state is left as soon as attained), and the second term represents the depletion of the last remaining stock.

Similarly,

$$\frac{d\Pr[A,S^*,t]}{dt} = -\lambda_C \Pr[A,S^*] + \lim_{S \to S^*} (f_A[S,t] \cdot \Delta_A[p_A[S]]) .$$

(26)

### 5.2 Stationary distribution

The study of stationary distribution can use directly the preceding analysis. We denote the stationary densities by $f^*_\sigma[S]$ for all $S \in (0,S^*)$. Define $\phi_C[S] \equiv f_C[S] \cdot \Delta_C[p_C[S]]$ and $\phi_A[S] \equiv f_A[S] \cdot \Delta_A[p_A[S]]$ (density flows). Dropping the time-dependency factor, and replacing the rates of variation of the stocks by their equilibrium values, equations (23,24) become the system of *ordinary*...\(^{13}\)This expression can be derived from (22) with $S_1 = 0$ and by letting $S_2$ converge to 0.
differential equations
\[ \frac{d\phi_A}{dS} = \lambda_A f^*_C - \lambda_C f^*_A, \quad (27) \]
\[ -\frac{d\phi_C}{dS} = \lambda_A f^*_C - \lambda_C f^*_A. \quad (28) \]

We also have from (25,26)
\[ \Pr[0] = \frac{1}{\lambda_A} \lim_{S \to 0} \phi_C, \quad (29) \]
\[ \Pr[S^*] = \frac{1}{\lambda_C} \lim_{S \to S^*} \phi_A. \quad (30) \]

Remark that
\[ -\phi_C[S] = \phi_A[S]. \quad (31) \]

Indeed, consider the open system \{ \((C, s), (A, s)\) | \(s \in [0, S]\) \}, this equation states that, in a stationary distribution, density flows in (at \(S\) for state \(C\)) equal flows out (at \(S\) for state \(A\)). Jumps do not matter since they happen within the system.

Equations (27) and (28) collapse to:
\[ \frac{d\phi_A}{dS} = -\left( \frac{\lambda_A}{\Delta_C[p_C[S]]} + \frac{\lambda_C}{\Delta_A[p_A[S]]} \right) \phi_A. \quad (32) \]

This first order ordinary differential equation is well defined for \(S \in ]0, S^*[\) and can be solved numerically. The Cauchy-Lipschitz theorem is applicable.

**Algorithm 2 (Stationary distribution)**

1. Calculate equilibrium prices \(p_C[S]\) and \(p_A[S]\).
2. Fix arbitrarily \(\phi[S]\) as an initial condition for some \(S \in (0, S^*)\).
3. Solve numerically the differential equation (32) over \(]0, S^*[\).
4. Calculate conditional densities \(f^*_A\) and \(f^*_C\).
5. Calculate the integrals over \(]0, S^*[\) of \(f^*_A\) and \(f^*_C\).
6. Remark that \(\Pr[S^*] = 0\). Use step 5 to calculate the residual \(\Pr[0]\) using the facts that \(\Pr[C] = \frac{\lambda_A}{(\lambda_C + \lambda_A)}\) and \(\Pr[A] = \frac{\lambda_C}{(\lambda_C + \lambda_A)}\).
7. Normalize \(f^*_A\) and \(f^*_C\) so that the total probability mass equals 1.
Step 3 must be analyzed in detail. Indeed, \( \Delta C[p_C[0]] = \Delta C[p_C^*] = 0 \) and \( \Delta A[p_A[S^*]] = \Delta A[p_A^*] = 0 \), meaning that \( \phi \) might diverge in such a way that normalization is impossible (integrals at step 5 could diverge). In fact, we check in Appendix A.7, that

\[
\int_0^{S^*} f_C[S]dS < \infty \text{ and } \int_0^{S^*} f_A[S]dS < \infty. \tag{33}
\]

Remark also that the integrals in step 5 can be calculated as accurately as needed, implying that the residual for \( Pr[0] \) in step 6 can be computed with the same accuracy.\(^{14}\)

The numerical analysis gives instructive results on the overall behavior of the economy. How frequent are stockouts, i.e. how much is \( Pr[S^*] = 0 \) compared to \( Pr[C] = \left(\frac{\lambda_C}{\lambda_C + \lambda_A}\right) \)? Is the economy often close to having maximum stocks or is \( S^* \) a practically unapproachable limit? The last question can be addressed theoretically by characterizing the shape of the density of the stationary equilibrium around \( S^* \). Here we can identify which are the critical parameters that determine the regime of the economy.

Figure 4 shows the stationary densities for the parameters in Table 1. We find \( Pr[0] = .1 \), \( Pr[S^*] = 0 \). In fact \( \lim_{S \to 0} f_C = +\infty \), but \( f_C \) is approximately proportional at 0 to \( 1/\sqrt{S} \), meaning that the probability of \( C \) remains finite (see equation 29). This high density around 0 comes from the fact that the rate of consumption of the stocks decreases steeply as \( S \) approaches zero. The high density on the left of \( S^* \) is explained by the fact that accumulation slows down as the stock approaches \( S^* \) (see equations (18,19) about drainage speed and time).

In contrast to 0, \( S^* \) is never attained, as we mentioned in Subsection 4.2. Nevertheless, as Proposition 4 shows, the probability mass can be quite concentrated, under precise circumstances, in the neighborhood of the maximum.

**Proposition 4** Let

\[
K_{S^*} = \frac{2\lambda_C}{\sqrt{(r+\lambda_C)^2 + 4\Delta_A[p_A^*]\lambda_C M - r - \lambda_C}} \tag{34}
\]

\[
\text{with } M = \frac{[(r+\lambda_A)(r+\lambda_C) - \lambda_A \lambda_C]p_A^* + (r+\lambda_A + \lambda_C)c}{-\lambda_C \Delta_C \left[ \frac{r+\lambda_C}{\lambda_C} p_A^* + \frac{c}{\lambda_C} \right]} > 0. \tag{35}
\]

At \( S^* \), \( f_C \) is of the order of \( (S^* - S)^{K_{S^*}} \) and \( f_A \) is of the order of \( (S^* - S)^{K_{S^*}-1} \).

\(^{14}\)The alternative method would be to use property (29); however, the numerical accuracy of the limit of \( \phi_C \) at 0 is not sufficient to recommend this procedure.
Consequently,

1. If \( K_{S^*} < 1 \): \( f_A \) increases and diverges as \( S \rightarrow S^* \). Though the maximum is never attained, any neighborhood of \( S^* \) has a positive probability.

2. If \( 1 < K_{S^*} < 2 \): \( f_A \) converges to 0 at \( S^* \) with vertical negative slope. The system is close to the maximum with a positive probability.

3. If \( K_{S^*} > 2 \): \( f_A \) converges to 0 at \( S^* \) with a null slope. The economy is almost surely far from the upper bound.

Given the discontinuous nature of the comparative statics, singular cases with either \( K_{S^*} = 1 \) or \( K_{S^*} = 2 \) would require higher order approximations than the one used in Appendix A.8 to be described.

The understanding of the conditions above is relatively complex since all the fundamental parameters play a role. In particular, no simple comparative statics with respect to \( r \) or \( \lambda_C \) emerge. In contrast, the effects of \( c \), \( \lambda_A \) are obvious

\[
\frac{\partial K_{S^*}}{\partial c} < 0; \quad \frac{\partial K_{S^*}}{\partial \lambda_A} < 0. \tag{36}
\]

In the linear case, where in particular \( \Delta_X[p^*_A] = \beta_A \), we have

\[
\frac{\partial K_{S^*}}{\partial \beta_C} > 0; \quad \frac{\partial K_{S^*}}{\partial \beta_A} < 0; \quad \frac{\partial K_{S^*}}{\partial p^*_C} < 0; \quad \frac{\partial K_{S^*}}{\partial p^*_A} < 0. \tag{37}
\]
The comparative statics on $K_{S^*}$, together with the ones on $S^*$ exposed in the comments of Proposition 2, outline a notion of flexibility: the higher $K_{S^*}$, the less flexible the economy is. Excess supply functions measure the response of prices to given variations in stocks. Small maximum stocks correspond to flexible economies for which large storage would be useless, and accordingly the economy has, statistically, enough time to approach this modest target during abundance period. On the contrary, large maximum stocks mean that the economy with seize (almost) any opportunity to accumulate, which happens in economies where building stocks is a costly process. Accordingly, it is very likely that the random alternation between abundance and scarcity episodes will keep the economy far from the bliss point.

6 Applications and extensions

In this Section, we extend the model by assessing the impact of three kinds of constraints: politically imposed bounds on prices, nonnegligible injection and release costs and limited storage capacity.

Analyzing the impact of a constant price on the dynamic system allows a comparison of the results with those proposed by the abundant literature on stabilization. Following on from this, we show that nonnegligible injection and release fees can be modelled as parallel shifts in the functions $p_A[S]$ and $p_C[S]$. The main results of our analysis are unaffected by this generalization. Finally, assuming that storage capacity is exogenously constrained, we show that in the accumulation phase, the maximal stock is attained in finite time. Moreover, the price for storage service suddenly jumps above marginal cost when capacity saturates.

6.1 Stabilization, storage and persistent crises

Assume that a central authority imposes a constant price $p^*$. A price below $p^*_A$ would not be sustainable in the long run (stock will be drained out shortly). A price above $p^*_C$ would cause never ending accumulation, which would be uneconomical. So, the relevant policies consider $p^*_A < p^* < p^*_C$. Remark that if we preclude rationing, the policy is not strictly applicable since the price must turn to $p^*_C$ when stocks are empty in state $C$. With rationing, the price may remain formally at $p^*$, but the marginal shadow value of the commodity would be $p^*_C$ anyway.

To summarize the effect of the policy, the simplest approach is to search
for stationary distribution. We can solve (32), i.e.

\[ \frac{d\phi_A}{dS} = - \left( \frac{\lambda_A}{\Delta_C} + \frac{\lambda_C}{\Delta_A} \right) \phi_A \text{ for all } S > 0, \tag{38} \]

where \( \frac{\lambda_A}{\Delta_C} + \frac{\lambda_C}{\Delta_A} \) here is a constant (with a constant price, \( \Delta_C < 0 \) and \( \Delta_A > 0 \) are constant). Define \( \bar{p} \) as the solution to the equation \( \lambda_A \Delta_A[p] + \lambda_C \Delta_C[p] = 0 \).

If \( p^* < \bar{p} \), then \( \frac{\lambda_A}{\Delta_C} + \frac{\lambda_C}{\Delta_A} > 0 \iff \lambda_A \Delta_A + \lambda_C \Delta_C < 0 : \) on average, the economy draws on the stocks. This implies that \( \phi_A \) is decreasing and the density is a decreasing exponential: lower stocks are more likely. The distribution has an unbounded support, empty stocks in crisis is an event of positive probability during which the price is \( p^*_C \).

If \( p^* > \bar{p} \), then \( \frac{\lambda_A}{\Delta_C} + \frac{\lambda_C}{\Delta_A} < 0 \iff \lambda_A \Delta_A + \lambda_C \Delta_C > 0 : \) on average, the economy piles up stocks. This implies that \( \phi_A \) is increasing unboundedly with respect to \( S \). Higher stocks being increasingly likely, normalization is impossible; in other words there is no well defined stationary distribution. Stocks diverge to infinity with probability one and stabilization, in this sense, succeeds.

The case \( p^* = \bar{p} \) is intriguing. The economy has no tendency to pile up nor to drain out stocks. All positive levels of the stocks are equally likely (the stationary density is flat), meaning that the behavior of the system in the long run is unpredictable.

Stabilization should not be understood in the narrow sense of averaging the price that would be observed in the absence of storage capabilities. Remark indeed that \( \bar{p} \), which is the critical threshold, could be higher or lower than the average no-storage price \( \frac{\lambda_A}{\lambda_A + \lambda_C} p_A^* + \frac{\lambda_C}{\lambda_A + \lambda_C} p_C^* \). This depends on the sensitivity of excess supply functions to price variations.

The conclusion is straightforward: perfect price stabilization can be reached only if the economy is prepared to let stocks go to infinity. The analysis above is easily extended to the case of limited storage capacity. Any upper bound on stocks leaves positive probability on empty stocks. In that case, the probabilities of full storages and stockouts depends on the policy \( p^* \) chosen.

### 6.2 Injection and release costs

Denote unit injection cost by \( i \) and unit release cost by \( s \). Assume that in each state \( \sigma = A, C \), and for any stocks level \( S \), there are markets for the gas outside and inside the reservoir, the prices being respectively \( p_{\sigma}[S] \) and \( p_{\sigma}'[S] \). The (competitive) market equilibrium between outside and inside gases implies that, whenever \( S > 0 \),

\[ p_A[S] + i = p_{A}'[S] \text{ and } p_C[S] = p_{C}'[S] + s. \tag{39} \]
The structure of the system of equations is preserved, with \( p'_I \) replacing \( p_σ \). No arbitrage conditions read

\[
\Delta_C[p'_C + s] \cdot \frac{dp'_C}{dS} = (r + \lambda_A)p'_C - \lambda_A p'_A + c, \tag{40}
\]
\[
\Delta_A[p'_A - i] \cdot \frac{dp'_A}{dS} = (r + \lambda_C)p'_A - \lambda_C p'_C + c. \tag{41}
\]

Remark that the excess supply functions are shifted, thus boundary conditions are

\[
p'_C[0] = p'^*_C - s, \tag{42}
\]
\[
p'_A[S^*] = p'^*_A + i. \tag{43}
\]

The range of \( p'_I \) is narrower than that of \( p_σ \): the minimum is higher, the maximum is lower. As a result, the condition ensuring that there is storage in equilibrium is more restrictive than the one in Proposition 1 (Point 4), i.e. in the linear case

\[
p'^*_C - s > \left( \frac{r + \lambda}{\lambda_C} \right) (p'^*_A + i) + \frac{c}{\lambda_C}. \tag{44}
\]

The phase diagram enables us to show that \( S^* \) is decreasing with respect to the cost parameters \( s \) and \( i \). The rest of the comparative statics is identical.

6.3 Limited storage capacity

If the total storage capacity \( \overline{S} \) exceeds \( S^* \), then the unconstrained trajectory remains sustainable; else, rational storers anticipate that boundary conditions are modified.

As long as some capacity is vacant, then storage price per unit of gas (per unit of time) remains equal to marginal cost \( c \); the system of equations is exactly the same as the one without any constraint, so the equilibrium is described by a trajectory in region \( I \) of the phase diagram. Trajectories below the unconstrained equilibrium start on the vertical axis at a given price for \( S = 0 \) and stop on the horizontal axis on the right of \( \Omega \) for a maximum stock which is smaller than \( S^* \). There is a unique trajectory such that this maximum stock equals exactly \( S \). It describes the unique equilibrium with limited storage capacity. See for example the dashed trajectory below the bold one in Figure 1.

In the accumulation phase, the price for storage service suddenly jumps above marginal cost when capacity is saturated. We denote it by \( \pi_A. \)\(^\text{15}\) Given

\(^{15}\)In case of crisis, the stock immediately starts being used so that state \((C, S = \overline{S})\) does not last. This implies that \( \pi_C \), the price of storage services for congestion during the crisis, has no measurable economic effect.
that \( p_A[S] = p_A^* \), the no-arbitrage argument in state \((A, S = S)\) can be expressed
\[
\lambda_C(p_C[S] - p_A^*) = rp_A^* + \pi_A.
\]
(45)
The LHS measures the potential profit from holding stocks and the RHS the cost. Given that 
\( p_C[S] > r + \frac{\lambda_C}{\lambda_C}p_A^* + c \lambda_C \) (the terminal point is on the right of \( \Omega \) in Figure 1), we have \( \pi_A > c \).

In contrast to the unconstrained case, the maximal stock is attained in finite time if abundance lasts long enough. This explains that the jump in the price of storage services (a discontinuity) is consistent with a continuous price function \( p_A[S] \) (continuity is necessary for no-arbitrage): before the capacity is full, the price \( p_A[S] \) decrease steadily; storers incur non-negligible capital losses if the state does not change; this depreciation term does not converge to zero as the maximal stocks are reached; this term is relayed by cost \( \pi_A > 0 \) when the constraint becomes binding.

7 Conclusion

Our model has fully described the behavior of a Markov economy in which storage dynamics are determined by random occurrence of crises. Overall, we have proved the quite appealing notion of “flexible economy”. We have proved that in equilibrium, a more flexible economy (i.e. better able to absorb shocks via production and consumption changes), is less keen to build up large stocks and is much more likely (in terms of probability) to hold maximum stocks. If the reluctance to build large stocks is intuitive, since overall, the value of stocks (or the convenience yield) decreases when an economy can promptly react to a shock, release dynamics are less intuitive. We show that flexible economies go fast towards maximum stocks and just stay there until a shock leads to fast drainage, while inflexible economies incur permanent movement of their stocks, and over a wider interval. This relationship between flexibility and maximum stocks is a result of interest. On this ground, it could be argued that security of supply policies for energy or banking rules for emission rights, which are never neutral with respect to the market equilibrium, should not be set equally across European states, inasmuch as their capabilities to repond to shocks is heterogeneous.

References


A Appendix

A.1 Phase diagram

Compared to \((AA')\), \((CC')\) cuts the horizontal axis with a smaller value of \(p_C\). It suffices to inject \(p_A = p^*_A\) in both equations and to check that

\[
\frac{\lambda_A}{r + \lambda_A} p^*_A - \frac{c}{r + \lambda_A} < \frac{r + \lambda_C}{\lambda_C} p^*_A + \frac{c}{\lambda_C}.
\]  

(46)

This is obvious.

To show that \((CC')\) cuts the vertical axis with a larger value of \(p_A\) than \((AA')\), we inject \(p_C = p^*_C\) into both equations and check that the following equation remains true (obvious)

\[
\frac{r + \lambda_A}{\lambda_A} p^*_C + \frac{c}{\lambda_A} > \frac{\lambda_C}{r + \lambda_C} p^*_C - \frac{c}{r + \lambda_C}.
\]  

(47)

A.2 Proof of Proposition 1

1. and 2. Price functions are continuous and the stocks vary continuously with respect to time, thus the support of stocks is necessarily an interval.

Assume that over some interval \(J\) of stocks, \(\Delta_C[p_C[S]] \geq 0\) and \(\Delta_A[p_A[S]] \geq 0\) (accumulation only) or \(\Delta_C[p_C[S]] \leq 0\) and \(\Delta_A[p_A[S]] \leq 0\) (drainage only). Clearly, interval \(J\) can be traversed once at most in history. Consequently, interval \(J\) cannot be part of the equilibrium support of the stocks.

If over some interval, \(\Delta_C[p_C[S]] \geq 0\) (i.e. \(p_C[S] \geq p^*_C\)) and \(\Delta_A[p_A[S]] \leq 0\) (i.e. \(p_A[S] \leq p^*_A\), accumulation during crises is motivated only by the fact that the price is expected to rise if the economy stays in crisis (an episode of abundance causes a negative shock on the price). This means that \(dp^*_C[S]/dS > 0\). In consequence, the price in state \(C\) is unbounded as well as the support of \(S\), since any length for an episode of scarcity has positive probability to be exceeded. Such a bubble is unreasonable since it would imply unbounded storage capacity (a transversality condition would translate this common sense remark into mathematical language). These arguments show that \(\Delta_C[p_C[S]] \leq 0\) (i.e. \(p_C[S] \leq p^*_C\)) and \(\Delta_A[p_A[S]] \geq 0\) (i.e. \(p_A[S] \geq p^*_A\)).
Remark now that if the lower bound of the support were strictly positive, this would mean that a certain quantity of the commodity would be permanently frozen. Denote this level by $S_{\text{min}}$. Necessarily, $p_C[S_{\text{min}}] = p_C^*$. meaning that if the economy stays in crisis for a long time (a possible event), storers have to pay storage costs without compensation in potential price movements. Consequently, support is bounded below by 0 ($S_{\text{min}} = 0$).

3. If $p_C[0] < p_C^*$, final demand would exceed production for $S = 0$, which is impossible with empty storages. This proves that the trajectory starts on the vertical axis ($p_C[0] = p_C^*$).

Assume that there is an $\varepsilon > 0$ such that $p_A$ stays larger than $p_A^* + \varepsilon$ as $S$ increases. Given the phase diagram, $p_A$ reaches its minimum on the straight line $(AA')$, if the trajectory starts in $I$. In any case, as $S$ increases, the trajectory enters in $II$, then in $III$, implying that $p_A$ overshoots $\frac{r + \lambda_A}{\lambda_A} p_C^* + \frac{c}{\lambda_A}$ (intersection between $(CC')$ and vertical axis). In other terms, for any large enough $S$, $p_A$ overshoots $p_A^*$ while $p_C$ remains below $p_C^*$. Thus, as $S$ continues to grow, $x_A'/x_C'$ remains finite whether or not $p_A$ tends towards infinity. We conclude that any trajectory in $III$ reaches the vertical axis $p_C = p_C^*$ for a finite value of the stock. At this point, drainage stops in state $C$, but accumulation continues in state $A$ ($x_A > 0$), meaning that the stock is never going to be used in the future, which is uneconomical (see point 1 in this proof).

We conclude from the contradiction that accumulation must stop in state $A$ for some stocks $S^*$; thus necessarily $p_A[S^*] = p_A^*$. Remark that this can only happen in $I$ on the horizontal axis at point $\Omega$.

4. From $(AA')$, we have

$$\begin{align*}
(r + \lambda_C)p_A[S^*] - \lambda_C p_C[S^*] + c &= 0 \\
\Rightarrow \quad p_C[S^*] &= \frac{r + \lambda_C}{\lambda_C} p_A^* + \frac{c}{\lambda_C}
\end{align*}$$

(48)

i.e.

$$p_C[S^*] = \frac{r + \lambda_C}{\lambda_C} p_A^* + \frac{c}{\lambda_C}$$

(49)

This corresponds to $\Omega = (\frac{r + \lambda_C}{\lambda_C} p_A^* + \frac{c}{\lambda_C}, p_A^*)$. For this intersection to exist, i.e. for $I$ not to be empty, a sufficient and necessary condition is

$$(r + \lambda_C)p_A^* + c \leq \lambda_C p_C^*.$$ 

(50)

5. We show that there is a unique trajectory passing through $\Omega$. The Cauchy-Lipschitz Theorem cannot be applied since the system is singular at $\Omega$. We use the following argument: choose any starting point in the interior of $I$, denoted by $(p^0_C, p^0_A)$; it is necessarily nonsingular. The trajectory passing through this point is unique (Cauchy-Lipschitz). Consider the point $(p^0_C, p^0_A + \varepsilon)$ where $\varepsilon$ is some small real. Straightforward calculations show that the slope of the trajectory passing
through \((p^0_C, p^0_A + \varepsilon)\), which is positive, decreases as \(\varepsilon\) increases. One can directly reason on
\[
dp_A/dp_C = \frac{\Delta_C[p_C]}{\Delta_A[p_A]} \frac{(r + \lambda_C)p_A - \lambda_C p_C + c}{(r + \lambda_A)p_C - \lambda_A p_A + c}.
\] (51)

This means that trajectories move apart as \(S\) increases, i.e. as they approach \(\Omega\). The consequence is that there cannot be multiple trajectories through \(\Omega\). This proves existence and uniqueness.

### A.3 Proof of Proposition 2

We first determine how trajectories move in the phase diagram as parameters change. Rewrite the system of ODE in compact form as
\[
p'_C = P_C(p_C, p_A, c, r, \lambda_A, \lambda_C) \quad \text{or simply } P_C (> 0 \text{ in region } I),
\] (52)
\[
p'_A = P_A(p_C, p_A, c, r, \lambda_A, \lambda_C) \quad \text{or simply } P_A (< 0 \text{ in region } I).
\] (53)

Note that \(\frac{\partial p_C}{\partial c} = 1/\Delta_C[p_C] < 0\) and \(\frac{\partial p_A}{\partial c} = 1/\Delta_A[p_A] > 0\), thus \(p'_A/p'_C = P_A/P_C\) decreases as \(c\) increases (all trajectories in \(I\) are flatter). Similar observations prove that all trajectories in \(I\) are also flatter when \(r\) increases, when \(\lambda_A\) increases and when \(\lambda_C\) decreases.

We can now position equilibrium trajectories as parameters change. Increasing \(c\) or \(r\), or decreasing \(\lambda_C\), move \(\Omega\) to the right; increasing \(\lambda_A\) has no effect on \(\Omega\). In all cases, the equilibrium trajectory moves below the former one: to each \(p_C\) is associated a smaller \(p_A\).

Remark that \(\frac{ds}{dp_C} = 1/P_C < 0\), thus
\[
S = -\int_{p_C[S]}^{p_C} \frac{dp_C}{P_C} \quad \text{(summation along the equilibrium trajectory).}
\] (54)

Since \(\Omega\) goes to the right as \(c\) increases, the range of \(p_C\) becomes smaller; it remains to be verified that \(1/P_C\), as a function of \(p_C\), is also smaller. For example, along the equilibrium trajectories, for a fixed \(p_C\)
\[
\frac{dP_C}{dc} = \frac{1}{\Delta_C[p_C]} + \frac{\partial p_A}{\partial p_C} \times \frac{\partial P_C}{\partial p_A} < 0.
\] (55)

\((P_C\) grows in absolute value and thus \(1/P_C\) decreases in absolute value.) This proves that as \(c\) increases, a given price is associated with a smaller \(S\). Similar reasonings can be applied to the other parameters to prove the claims.
A.4 Proof of Proposition 3

We have

\[ P_C = \frac{(r + \lambda_A)p_C - \lambda_A p_A + c}{\beta_C(p_C - p^*_C)}, \quad (56) \]
\[ P_A = \frac{(r + \lambda_C)p_A - \lambda_C p_C + c}{\beta_A(p_A - p^*_A)}. \quad (57) \]

Clearly, trajectories in \( I \) are steeper with a higher \( \beta_C \) or a smaller \( \beta_A \). Remark that the frontier of \( I \) (\( \Omega \) in particular) is unchanged in this comparative statics. Remark also (this concerns point 2) that a proportional increase of \( \beta_C \) and \( \beta_A \) does not change the trajectories (but a given point corresponds to a different \( S \)).

The type of reasoning used in the proof of Proposition 2 can now be applied to show the claims.

The comparative statics with respect to \( p^*_C \) and \( p^*_A \) require further precautions. In the former, remark that trajectories are steeper with a higher \( p^*_C \) (\( p_C < p^*_C \)) and that \( I \) is extended to the right (trajectories are simply going further to the right). These two effects concur to increase the price for given stocks. In the latter, trajectories are flatter with a (say) smaller \( p^*_A \) but \( \Omega \) moves along down (\( AA' \)). The first effect decreases prices, hence point 1, but the second could lead to a higher \( S^* \) (a smaller function is integrated over a longer interval, since the range of \( p_C \) increases, see equation 54).

A.5 Equivalent expressions for prices

On the right of 0. We have

\[ x_C[S] = \int_{p^*_C}^{p_C[S]} \Delta_C[p] dp, \quad (58) \]

thus, writing first-order approximation on both sides we get

\[ K_C S + o(S) = \frac{1}{2} \Delta_C[p^*_C](p_C[S] - p^*_C)^2 + o(p_C[S] - p^*_C)^2, \quad (59) \]

which yields

\[ p_C[S] - p^*_C \sim -\sqrt{\frac{2K_C}{\Delta'_C[p^*_C]}} S^{1/2}. \quad (60) \]
On the left of \( S^* \). Given that, according to (7), \( p_C[S^*] \neq 0 \), we can approximate \( p_C[S] \) around \( S^* \) with \( p_C[S^*] + p_C[S^*](S - S^*) + o(S - S^*) \). We denote \( p_C[S^*] \) by \(-M\), with

\[
M = -\frac{(r + \lambda_A)(r + \lambda_C) - \lambda_A \lambda_C}{\lambda_C \Delta C}( C^2 p_A + \frac{(r + \lambda_A + \lambda_C) c}{\lambda_C} ) > 0. \tag{61}
\]

Given that

\[
x_A[S] = \int_{p_A[S]}^{p_A[S]} \Delta_A[p] \, dp,
\]
we can calculate that \( p_A[S] - p_A^* + o(p_A[S] - p_A^*) = \sqrt{\frac{2}{\Delta_A[p_A]} \Delta_A^2[S]} \), or equivalently \( p_A[S] - p_A^* = \sqrt{\frac{2}{\Delta_A[p_A]} \Delta_A^2[S]} + o(x_A^{1/2}[S]) \).

We plug these two equivalent expressions into (8), which yields

\[
x'_A = (r + \lambda_C) \sqrt{\frac{2}{\Delta_A[p_A]} \Delta_A^2[S]} + \lambda_C M(S - S^*) + o(S - S^*) + o(x_A^{1/2}), \tag{63}
\]

Consider now the ODE

\[
y' = (r + \lambda_C) \sqrt{\frac{2}{\Delta_A[p_A]} \Delta_A^2[S]} y^{1/2} + \lambda_C M(S - S^*) \] with \( y[S^*] = 0. \tag{64}
\]

The unique solution to (64) is \( K_A^2(S^* - S)^2 \) with

\[
K_A = \sqrt{(r + \lambda_C)^2 + 4 \alpha_A, \beta_A M r - \lambda_C} \frac{2 \alpha_A, \beta_A}{2 \alpha_A, \beta_A}. \tag{65}
\]

We show now that this exact solution of approximate ODE (64) is an approximation of the solution to ODE (63).

Consider the residual \( o(S - S^*) + o(x_A^{1/2}[S]) \) in the ODE (63). For all \( \varepsilon > 0 \), there is a left neighborhood of \( S^* \), denoted \( V_\varepsilon \), in which the absolute value of the residual is smaller than \( \varepsilon \times (S^* - S) \) and \( \varepsilon \times (x_A^{1/2}[S]) \). Consider the ODE

\[
y' = [(r + \lambda_C) \sqrt{\frac{2}{\Delta_A[p_A]} \Delta_A^2[S]} + \varepsilon] y^{1/2} + (\lambda_C M - \varepsilon)(S - S^*) \] with \( y[S^*] = 0. \tag{66}
\]

The solution to this equation is smaller than \( x_A \) on \( V_\varepsilon \): indeed, both \( x'_A \) and \( y' \) are negative, but if \( y > x_A \) for some \( S \) in \( V_\varepsilon \), it remains so for any larger stock because \( y' > x'_A \). This is in contradiction with the fact that \( y[S^*] = x_A[S^*] \). In other terms,

\[
x_A[S] \geq \left[ \sqrt{(r + \lambda_C + \sqrt{\frac{2}{\Delta_A}[\Delta_A^2[S] + 4 \alpha_A, \beta_A \alpha_A, \beta_A M - r - \lambda_C - \sqrt{\frac{2}{\Delta_A}]} \varepsilon})^2 (S^* - S)^2. \tag{67}
\]
A similar reasoning shows that

$$x_A[S] \leq \left[ \frac{\sqrt{(r+\lambda_C - \sqrt{\frac{\lambda_C}{2\beta_A}})^2 + 4\beta_A(\lambda_C M + \varepsilon) - r - \lambda_C + \sqrt{\frac{\lambda_C}{2\beta_A}}}}{2\beta_A} \right]^2 (S^* - S)^2. \tag{68}$$

These two inequalities give the approximation of $x_A$ at $S^*$.

### A.6 Statistical evolution from a known state

To fix ideas, denote the observed state at, say, date $t = 0$, by conjuncture $A$ and stocks $S_0$. Conditionally on staying in state $A$, the probability mass (initially 1) is attached to a unique level of the stocks; but this mass itself is eroded by potential jumps. Other states (except 0 and $S^*$) are associated with a density, as we shall develop now.

The mass point $S_{\text{max}}[t]$ (where the index max recalls that the support of the distribution is bounded above by this time dependent value) evolves following

$$\frac{dS_{\text{max}}}{dt} = \Delta_A[p_A[S_{\text{max}}]] > 0 \quad \text{with} \quad S_{\text{max}}[0] = S_0, \tag{69}$$

whereas the lower bound of the distribution follows

$$\frac{dS_{\text{min}}}{dt} = \Delta_C[p_C[S_{\text{min}}]] < 0 \quad \text{until} \quad 0 \quad \text{is reached, with} \quad S_{\text{max}}[0] = S_0. \tag{70}$$

Both values move deterministically. Clearly,

$$\Pr[A, S_{\text{max}}[t], t] = e^{-\lambda_C t}, \tag{71}$$

which is the probability that no crisis has ever happened since date 0.

States inside the interval $[S_{\text{min}}[t], S_{\text{max}}[t]]$ are associated with a positive density; outside the interval, density is null. States $(C, 0, t)$ and $(A, S_{\text{max}}[t], t)$ are mass points (the former only after some time has elapsed, so that $S_{\text{min}}$ has reached 0).

To fully characterize the statistical evolution from a known state, we prove the following preliminary lemma that explains how a pointwise probability becomes a density.

**Lemma 1**

$$\lim_{S \to S_{\text{max}}[t]} f_C[S, t] = -\frac{\lambda_C e^{-\lambda_C t}}{\Delta_C[p_C[S_{\text{max}}[t]]] + \Delta_A[p_A[S_{\text{max}}[t]]]}, \tag{72}$$
Proof. Consider states \( \{(C,S)|S \in [S_{\max}[t] - dS, S_{\max}[t]]\} \) with \( dS \) small. To calculate the probability of this event at date \( t \), we have to trace back histories that lead to these states.

Denote \( dt \) and \( dS_A \) the unique time interval and stock variation such that a jump from \((A, S_{\max}[t] - dS_A)\) to \((C, S_{\max}[t] - dS_A)\) at date \( t - dt \) followed by drainage between date \( t - dt \) and \( t \) has led to state \((C, S_{\max}[t] - dS)\).

Clearly, all the jumps happening from the current mass point between dates \( t - dt \) and \( t \) (and only these), give states in \([S_{\max}[t] - dS, S_{\max}[t]]\) at date \( t \).\(^{16}\) So a first-order approximation of the probability we seek is the probability that a jump from \( \{(A,S)|S \in [S_{\max}[t] - dS_A, S_{\max}[t]]\} \) to \( C \) has taken place between date \( t - dt \) and \( t \). This probability is \( \lambda_C e^{-\lambda_C t} dt \), thus

\[
\Pr[\{(C,S)|S \in [S_{\max}[t] - dS, S_{\max}[t]]\}] = \frac{\lambda_C e^{-\lambda_C t} dt}{dS}.
\]

We have to calculate the relationship between \( dS_C, dS_A, \) and \( dt \). From the stock dynamics we have

\[
dt = \frac{dS - dS_A}{\Delta_C[p_C[S_{\max}[t]]]} = \frac{dS_A}{\Delta_A[p_A[S_{\max}[t]]]}.
\]

The middle term is the time needed, given drainage speed, to pass from stocks \( S_{\max}[t] - dS_A \) to stocks \( S_{\max}[t] - dS \). The RHS is the time needed, given accumulation speed, to pass from \( S_{\max}[t] - dS_A \) to \( S_{\max}[t] \). After straightforward substitutions, we let \( dS \) go to 0 and prove the result.

We are now equipped with a complete set of equations to describe the dynamics. Indeed, (72) and (23,24) can be used to describe statistically the system over time. The exercise is numerically demanding.

A.7 Proof of convergence of Algorithm 2

Remark that the ODE commanding \( \phi_A \) can be written

\[
\frac{d\phi_A}{\phi_A} = -\left( \frac{\lambda_A}{\Delta_C} + \frac{\lambda_C}{\Delta_A} \right).
\]

On the right of \( S = 0, \Delta_C \to 0 \) so the RHS of (75) is equivalent to \(-\frac{\lambda_A}{\Delta_C}\), i.e., using (16), to \( \frac{K_0}{\sqrt{S}} \) where \( K_0 \) is a nonnegative real

\[
K_0 = \frac{\lambda_A}{\Delta_C[p_C[S_{\max}[t]]] \sqrt{K_C}}.
\]

\(^{16}\)Given the small size of the interval, we can neglect histories involving two jumps, so relevant histories can only consist of one jump from state \( A \) and some drainage.
Thus \( \lim_{S \to 0} \phi_A \) is finite and strictly positive. Indeed, for all \( \varepsilon > 0 \), there exists \( \eta \) such that for all \( S \leq \eta \),

\[
(1 - \varepsilon) \frac{K_0}{\sqrt{S}} \leq \frac{\phi_A'}{\phi_A} \leq (1 + \varepsilon) \frac{K_0}{\sqrt{S}} \tag{77}
\]

Take \( S_1 \) and \( S_2 \) both smaller than \( \eta \) with \( S_1 \leq S_2 \) and integrate the inequality above between these two reals. We find

\[
2(1 - \varepsilon)K_0(\sqrt{S_2} - \sqrt{S_1}) \leq \ln \frac{\phi_A[S_2]}{\phi_A[S_1]} \leq 2(1 + \varepsilon)K_0(\sqrt{S_2} - \sqrt{S_1}). \tag{78}
\]

This proves that \( \phi_A \) is bounded away from 0 (fix \( S_2 \) and let \( S_1 \) converge to 0).

So, at 0, \( f_A \) is finite and nonnegative whereas \( f_C \sim 0 \sqrt{S} \) where \( K_{fC} \) is some nonnegative real. This implies that, though the density \( f_C \) diverges at 0, its integral is well defined.

### A.8 Proof of Proposition 4

On the left of \( S^* \), \( \Delta_A \to 0 \) so the RHS of (75) is equivalent to \( -\frac{\lambda_C}{\Delta_A} \), i.e. \( \frac{K_{S^*}}{S^* - S} \), where \( K_{S^*} \) is a nonnegative real with

\[
K_{S^*} = \frac{\lambda_C}{\beta_A K_A}. \tag{79}
\]

For all \( \varepsilon > 0 \), there exists \( \eta \) such that for all \( S \geq S^* - \eta \),

\[
(1 - \varepsilon) \frac{K_{S^*}}{S^* - S} \leq -\frac{\phi_A'}{\phi_A} \leq (1 + \varepsilon) \frac{K_{S^*}}{S^* - S} \tag{80}
\]

Take \( S_1 \) and \( S_2 \) both larger than \( S^* - \eta \) with \( S_1 \leq S_2 \) and integrate the inequality between these two real numbers. We find

\[
-(1 - \varepsilon)K_{S^*} \ln \frac{S^* - S_2}{S^* - S_1} \leq -\ln \frac{\phi_A[S_2]}{\phi_A[S_1]} \leq -(1 + \varepsilon)K_{S^*} \ln \frac{S^* - S_2}{S^* - S_1}, \tag{81}
\]

i.e.

\[
\left[\frac{S^* - S_2}{S^* - S_1}\right]^{(1+\varepsilon)K_{S^*}} \leq \frac{\phi_A[S_2]}{\phi_A[S_1]} \leq \left[\frac{S^* - S_2}{S^* - S_1}\right]^{(1-\varepsilon)K_{S^*}}. \tag{82}
\]

This implies that \( \lim_{S \to S^*} \phi_A = 0 \), from which we can conclude that \( \Pr[S^*] = 0 \).

We can now derive a tight condition on the shape of the density function \( f_A \) around the upper bound \( S^* \). Indeed, given that \( \phi_A = f_A \cdot \Delta_A \),

\[
f_A[S] \text{ is proportional to } (S^*-S)^{K_{S^*}-1}. \tag{83}
\]

Equation (83) together with \( \phi_C = -\phi_A \) proves Proposition 4.